

Fundamentals of Air Dispersion Modelling

Fate and Transport Phenomena



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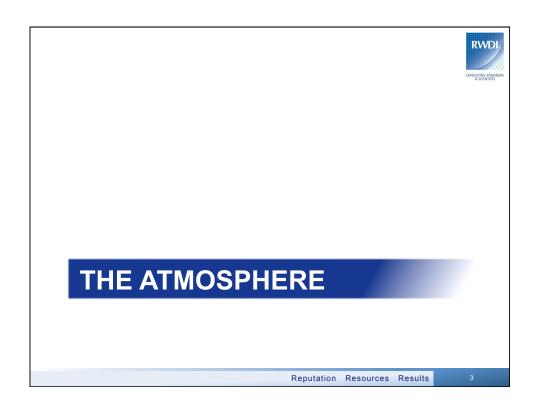
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Fundamentals of Air Dispersion Modelling



- Course overview
 - The earth's atmosphere
 - Basic air quality meteorology
 - Plume rise mechanics
 - The Gaussian Plume Model
 - Puff Models
 - Models Approved under O. Reg. 419/05
 - Models in the Appendix to O. Reg. 346
 - AERMOD
 - ASHRAE

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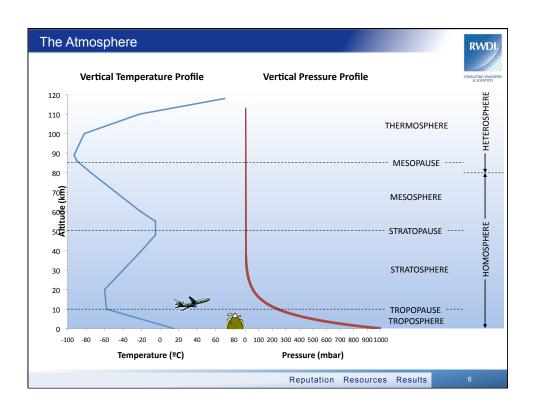




The Atmosphere



- The atmosphere is the thin layer above the surface of the earth that sustains pretty much all life as we know it.
- Some liken it to the thickness of the skin on an apple, if the apple were the earth.
- Despite it's relative thinness, it is complex, and broken up into many different layers, defined by temperature, pressure and composition.



The Atmosphere



- The temperature profile is perhaps the most complex.
- This has to do with the complex interaction of energy transfer and the changing chemistry of the atmosphere.
- By contrast, the pressure profile is quite simple.

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The Atmosphere



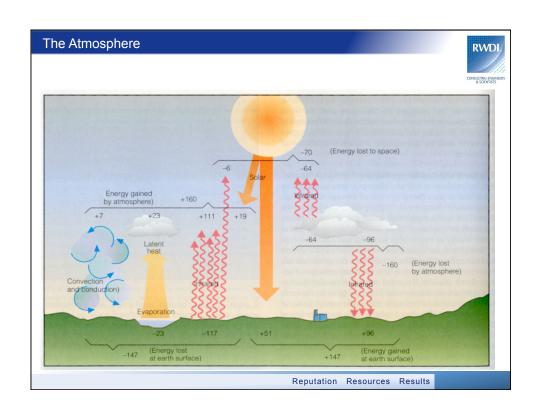
- The composition is divided into only two main categories:
 - Homosphere: The lowest layer, up to ~80 km, where the composition of the atmosphere is generally homogeneous. It also includes the "ozone layer", between ~10 and 60 km.
 - Heterosphere: Layer above ~80 km and into space, where the chemical composition is layered according to the molecular weight of the gases, with the heaviest near the bottom.

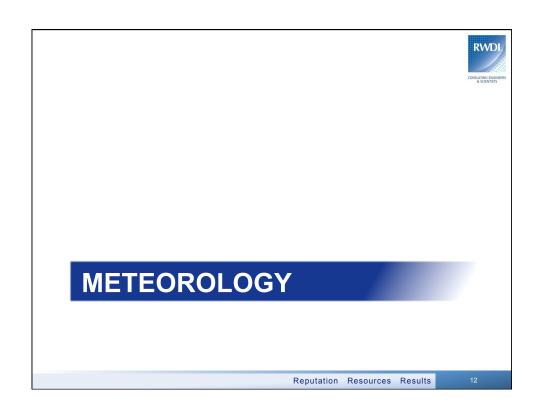
The Atmosphere **RWDI** SUBSTANCE VOLUME (%) CONCENTRATION (ppm)* 78.084 ± 0.004 780 900 Nitrogen 20.946 ± 0.002 209 400 Oxygen 9 300 0.934 ± 0.001 Argon Carbon dioxide 0.033 ± 0.001 315 18 Neon Helium 5.2 Methane 1.2 0.5 Krypton 0.5 Hydrogen 0.08 Xenon Nitrogen dioxide 0.02 0.01-0.04 Ozone Reputation Resources Results

The Atmosphere



- For typical air quality studies, we are most interested in the lower levels of the atmosphere (the troposphere and the homosphere).
- This region is also most affected by the exchange of radiation between the sun and the earth.
- The radiation exchange is the driving force behind what we refer to as meteorology.





Meteorology



- Within the lower levels of the troposphere and homosphere, yet another set of regions can be defined, this time based on meteorology.
- The meteorological conditions found in these regions will determine the transport of contaminants.
- In other words, the processes that drive meteorology will drive dispersion.

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Meteorological Regions **RWDI** MACRO-METEOROLOGICAL REGION Begins somewhere between 500 and 1000 metres above the earth. Horizontal scales on the order of 10's to 100's of kilometers. Free Atmosphere Surface friction does not affect wind velocity. Winds determined by pressure gradient force and the Coriolis effect. MESO-METEOROLOGICAL REGION Horizontal scales on the order of 10's of kilometers. Region of transition. Surface friction has a varying effect on the wind velocity. Winds are determined by a balance between the pressure gradient force, Coriolis effect, surface friction and temperature gradients. **Planetary** Boundary MICRO-METEOROLOGICAL REGION Layer • Usually extends from the surface to 50 to 100 metres above the earth. • Horizontal scales on the order of 100's of metres to a few kilometers. Surface Surface friction has the dominant effect on wind velocity. Layer Winds determined by surface friction and temperature gradients. Reputation Resources Results

Meteorological Regions - Boundary Layer



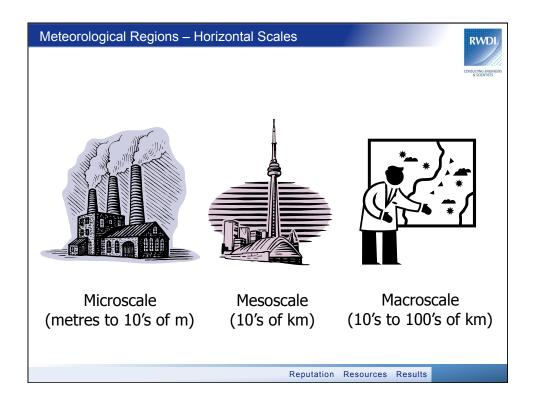
- The planetary boundary layer (PBL) is the region of the atmosphere that is adjusted to the surface underneath.
- The state of the PBL is determined by the properties of the surface (land use, Bowen ratio, roughness length, etc.)
- Quantities within the PBL, such as heat, momentum, water vapour or pollution tend to want to stay in the PBL.

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Meteorological Regions - Horizontal Scales



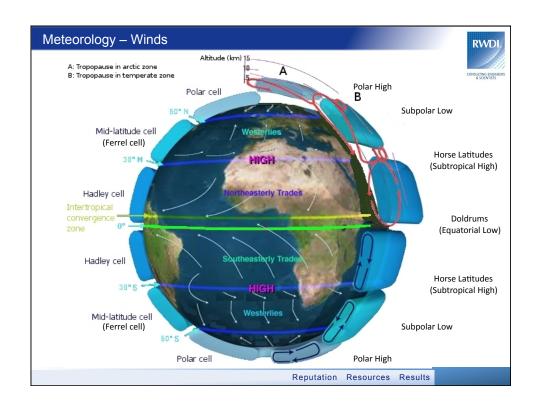
- Each region also identifies a relevant horizontal scale at which we consider winds and temperature profiles.
- Meteorological conditions on one scale can be very different from those on another scale (consider regional winds versus those experienced in a downtown core, or right next to a stack).



Meteorology - Winds



- At the synoptic (macro) scale, winds are caused by the difference in pressure between one location to another.
- These differences are caused by uneven heating of the earth's surface.
- These "synoptic" winds are then "bent" due to the Coriolis effect, which causes winds to deflect to the right (in the northern hemisphere).



Meteorology – Winds



- At the mesoscale level, winds will be impacted by geographical features, such as large bodies of water (e.g., sea breezes) and hills, mountains and valleys.
- At the microscale level, winds will be further impact by the influence of trees, buildings, and stacks (e.g., stack tip downwash).

Meteorology – Atmospheric Stability



- Our knowledge of winds allows us to begin estimating the direction and speed at which a contaminant will move.
- The next step is to estimate how the contaminant spreads out (disperses) as it moves downwind.
- The mechanism that drives this dispersion is turbulence.

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Meteorology - Atmospheric Stability



- There are two major forms of turbulence:
 - Thermal turbulence "the pilot has switched on the fasten seat-belts sign..."
 - Mechanical turbulence "brace for impact"
- Both affect dispersion, at different scales.
- Thermal turbulence is linked to the vertical temperature profile in the PBL, and we'll discuss this first.

Meteorology - Atmospheric Stability



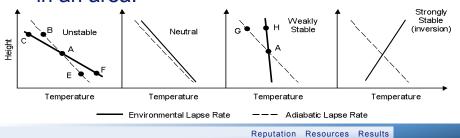
- Air temperatures normally decrease with height – the rate of decrease is called the lapse rate.
- · Under dry, adiabatic (no heat flows in or out of a system) conditions, this lapse rate would be 9.8 °C/km.
- This is known as the Dry Adiabatic Lapse Rate (DALR), and serves as an "ideal" or reference value, and represented by Γ .

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Meteorology - Atmospheric Stability



- In nature, what we actually observe is the "Actual Lapse Rate" or "Environmental Lapse Rate", often represented by γ .
- The difference between the two gives us an idea of the level of thermal turbulence in an area.



Meteorology - Atmospheric Stability



- Comparisons of actual lapse rate γ versus adiabatic lapse rate Γ provides information on atmospheric stability
 - Unstable conditions ($\gamma > \Gamma$) lead to enhanced vertical mixing and better dispersion of a plume
 - Neutral conditions ($\gamma \approx \Gamma$) lead to "normal" vertical mixing and "normal" dispersion of a plume
 - Stable conditions ($\gamma < \Gamma$) lead to diminished vertical mixing and retards dispersion of a plume

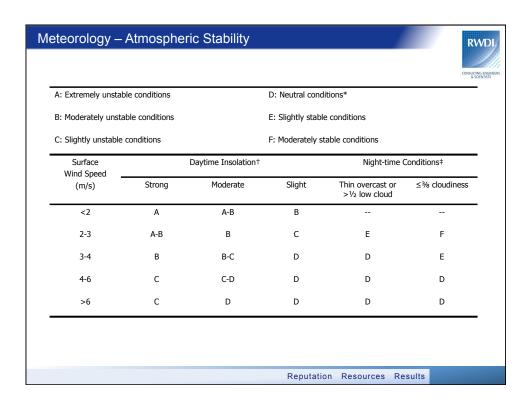
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Meteorology - Atmospheric Stability



- Several methods of defining atmospheric stability have been developed.
- The most common was the Pasquill Gifford (P-G) stability class system, which ranks stability classes from A (extremely unstable) through to F (moderately stable).
- Pasquill also developed a fairly simple method for estimating stability based on direct observations.

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Meteorology – Atmospheric Stability



- More advanced models (e.g., AERMOD), use a very different approach to estimating atmospheric stability.
- Mixing height and Monin-Obukhov length are the two parameters used for this.
- The mixing height is the vertical height in the atmosphere where the dispersion of pollutants can take place.

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Meteorology – Atmospheric Stability



- It rises during the day as solar radiation generates more and more turbulence.
- As the earth cools after the sun sets, the reverse happens, and the mixing height lowers back to near the surface.
- Above this layer, the atmosphere will be capped by a temperature inversion (stable layer).

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Meteorology - Atmospheric Stability



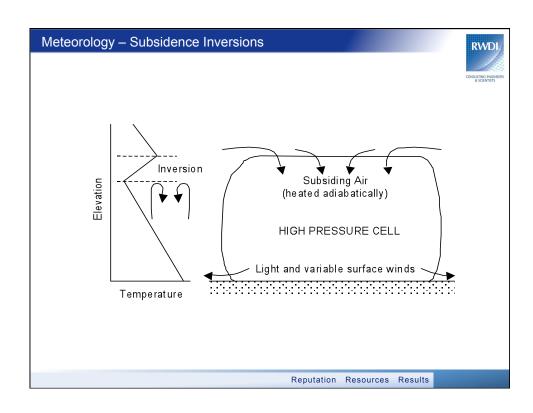
- Monin-Obukhov length is the height at which mechanically-produced turbulence is in balance with the buoyancy-produced turbulence.
- Below this level, mechanically-produced turbulence dominates, while above it the reverse is true.
- Models such as AERMOD use this to help further define atmospheric stability.

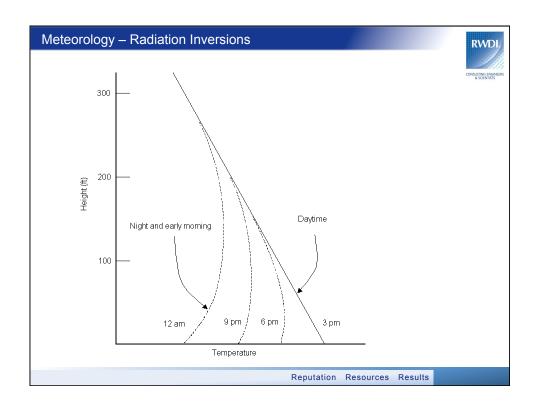
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Meteorology – Inversions



- An inversion is a rapid change in the vertical temperature profile, where there is a sudden transition into a stable layer.
- Inversions can act as a "lid" on lower regions of the atmosphere, restricting dispersion.
- Contaminants released above an inversion will also seldom impact the ground, however.

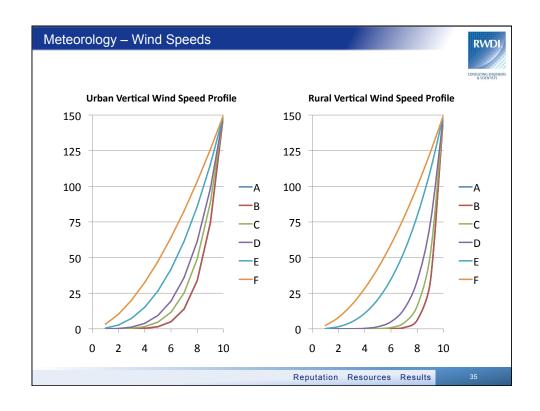


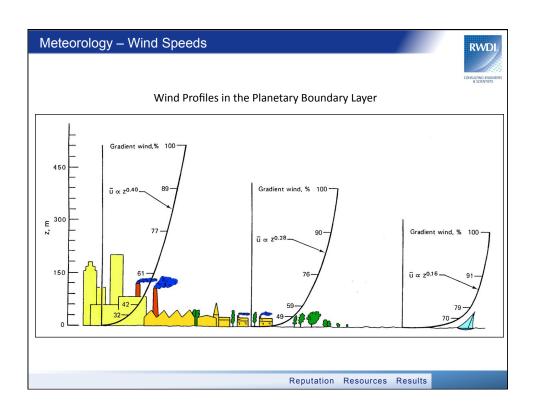


Meteorology – Wind Speeds



- One last item to consider is how obstacles, land use patterns and atmospheric stability combine to change the vertical wind speed profile.
- Obstacles or land-use patterns that produce friction near the surface, result in winds that are slower near the surface than relatively "smooth" areas.







PLUME RISE MECHANICS

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Plume Rise



 Plume rise (Δh) increases the effective height (H) of a stack, according to this basic formula:

$$H = h_s + \Delta h$$

- The physical height of the stack, h_s, is constant, but plume rise can vary considerably.
- Momentum and buoyancy of the plume both contribute to this phenomenon.

Plume Rise



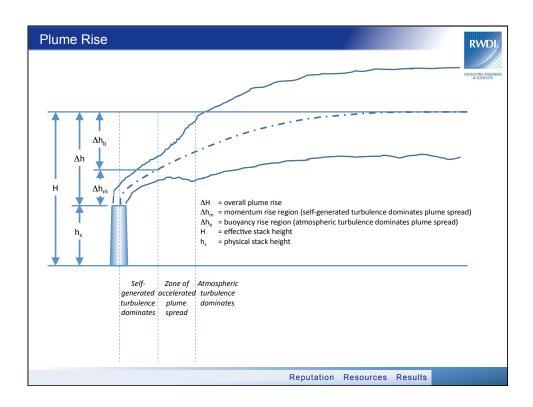
- Vertical momentum is a product of exit velocity (V_s) and the stack area (A_s), which can also be related to volumetric flow rate (Q_s) and stack diameter (D_s).
- The buoyancy force of an exhaust flow is created by a density differential between the exhaust gas and the ambient air.
 - Positive buoyancy corresponds to an exhaust that is lighter (less dense) than the surrounding air.

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Plume Rise



- Typically, momentum effects dominate initially, but these effects decay rapidly and are overtaken by buoyancy effects.
- If buoyancy effects are minor, momentum effects will dominate, and will be the primary mechanism for plume rise.
- If buoyancy effects are present however, they also tend to be longer-lived, and therefore tend to dominate.



There are two main methods for calculating plume rise:

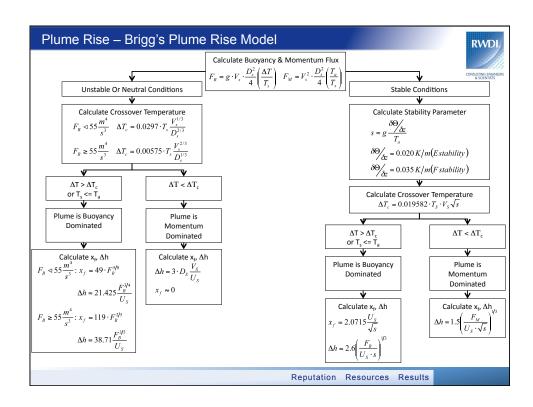
- Briggs Plume Rise Model
 - more complicated

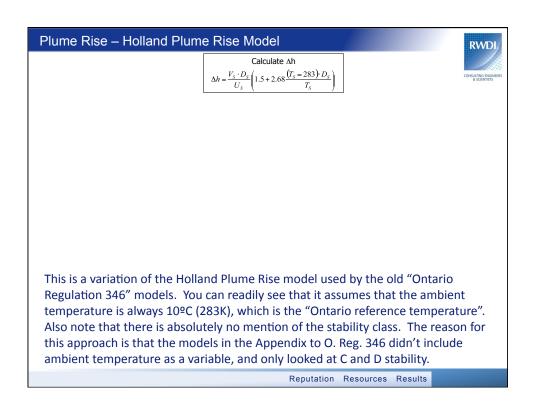
Plume Rise

- used in most current models (ISC, AERMOD)
- Holland Plume Rise Model
 - extremely simplified
 - used in MOE "Regulation 346" model

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Plume Rise - Brigg's Plume Rise Model



- In both of the models shown in the preceding slides, the following variables and units are used:
 - F_B = buoyancy flux (m⁴/s³)
 - F_M = momentum flux (m⁴/s²)
 - g = acceleration of gravity (= 9.8 m/s²)
 - V_s = stack exit velocity (m/s)
 - D_s = stack exit diameter (m)
 - T_s = stack exit temperature (K)
 - T_a = ambient temperature (K)
 - $\Delta T = T_s T_a =$ temperature differential (K)
 - xf = distance to final plume rise (m)
 - Δh = final plume rise (m)
 - U_s = wind speed at stack tip (m/s)
 - s = stability parameter (s⁻²)

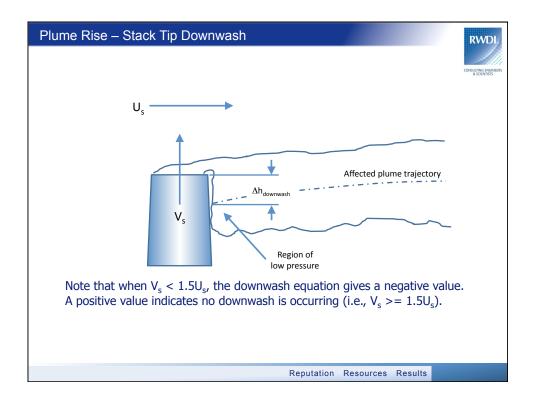
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Plume Rise - Stack Tip Downwash



- Stack tip downwash is a phenomenon that works against plume rise, and is cause by high wind speeds at the stack tip relative to the source momentum
- This can draw the plume it into the low pressure region on the rear of the stack.
- It is determined using a simple equation:

$$\Delta h_{downwash} = 2 \cdot D_s \left[\frac{V_s}{U_s} - 1.5 \right] \quad for V_s < 1.5 \cdot U_s$$



Plume Rise – Stack Tip Downwash



 With stack tip downwash added in, we now have the following complete equation for overall stack height, H:

$$H = h_s + \Delta h + \Delta h_{downwash}$$

- H is the required parameter used in the dispersion models used in the next chapter.
- Computer models handle this internally, which is obviously convenient!



GAUSSIAN PLUME MODEL

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Gaussian Plume Model



- A statistically derived model, developed through decades of research in wind tunnels, field experiments, and computer simulations.
- Currently the back-bone of the dispersion modelling field, and forms the basis of models such as AERMOD.
- Has limitations, but, for most of applications, it is extremely useful.



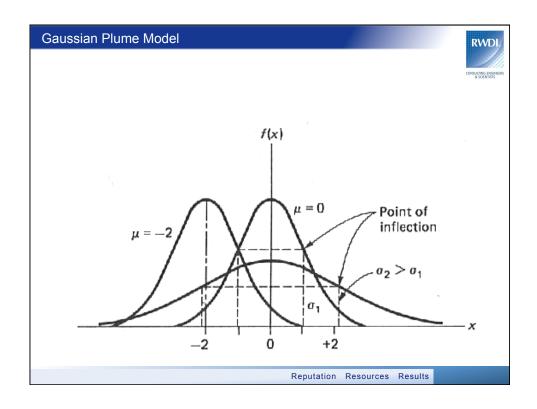
- There are a number of underlying assumptions that must be considered:
 - Steady state (no change with time).
 - Pollutants emanate from a continuous source.
 - The wind is always aligned to the x-direction.
 - Mass diffusion in the x-direction is negligible relative to the bulk transfer due to advection.
 - A constant wind speed at all x, y, z positions.
 - Effective diffusion coefficients are constant.
 - Plume species are inert (unreactive).
 - No sources or sinks occur (this assumption can be altered somewhat depending on the model).

Reputation Resources Results

Gaussian Plume Model



- Based on the Gaussian distribution, it relies heavily on the level of standard deviation (sigma, σ), which affects the spread of the curve.
- The greater the σ , the wider the curve.
- For pollutant transport, the greater the sigma, the greater the dispersion, and hence, the lower the concentration.

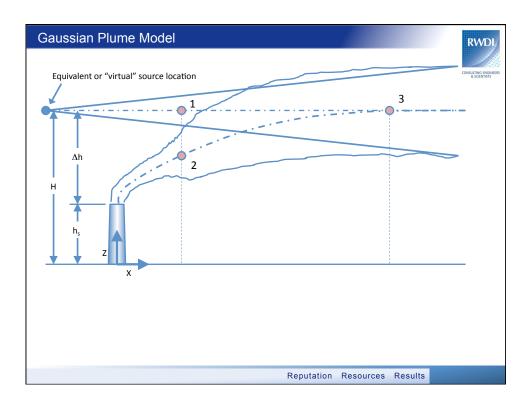




- The basic model looks at a traditional, unobstructed, vertically discharging stack, with effective height H.
- The dispersion of the contaminant in the vertical (z) and horizontal (y) directions is calculated as a function of downwind distance of the stack (x).
- Thus a prediction of the contaminant concentration at any location (x,y,z).



- Picture a plume rising from a stack, slowly spreading downwind as it goes.
- · Now forget that image.
- The model "reimagines" the plume as simply spreading from a single point in space, at a height "H" above ground, some distance upwind of the actual stack.
- Obviously, this causes problems near the stack (locations 1 and 2 on the next slide).





- The presence of the ground causes an issue because it is "impervious" to the spreading plume.
- While there could be deposition of material on the ground, either via dry or wet mechanisms, most of the plume hits the ground and is "reflected".
- The basic formula is modified to account for this "reflection".

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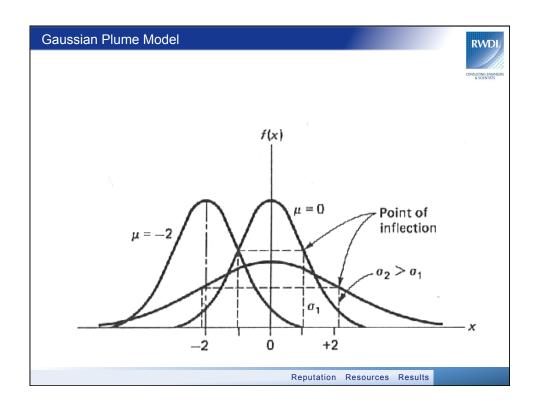
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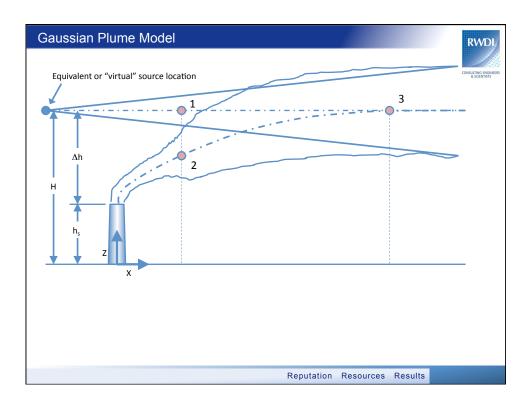




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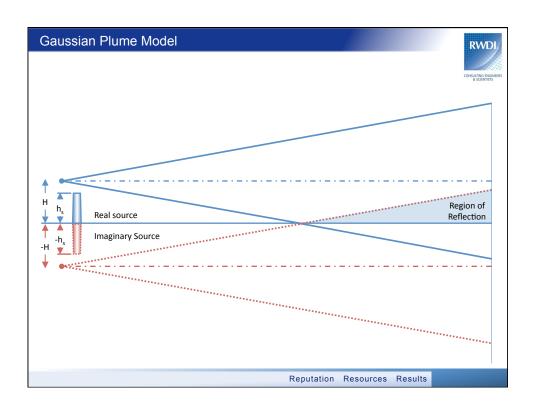


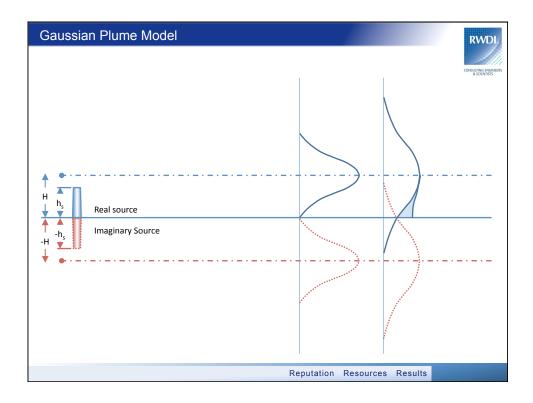
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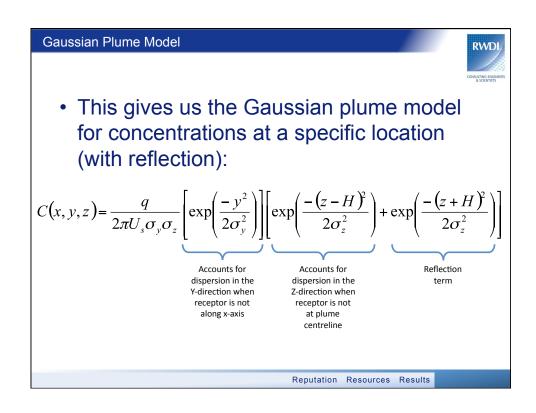




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- In the model shown in the preceding slide, the following variables and units are used:
 - C = contaminant concentration (g/m³)
 - x = receptor distance downwind from stack (m)
 - y = lateral (crosswind) distance between the receptor and the x-axis (m)
 - z = height of the receptor above grade (m)
 - q = contaminant emission rate (g/s)
 - U_s = wind speed at stack tip (m/s)
 - σ_v = lateral (cross-wind) dispersion coefficient (m)
 - $-\sigma_z$ = vertical dispersion coefficient (m)
 - H = effective stack height (m)

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Gaussian Plume Model



- σ_{y and} σ_z are can be determined through one of two methods:
 - graphs of standard deviation as a function of downwind distance.
 - equations that represent the curves on the abovementioned graphs.
- In addition, there are separate equations for urban or rural conditions.



• Rural conditions:

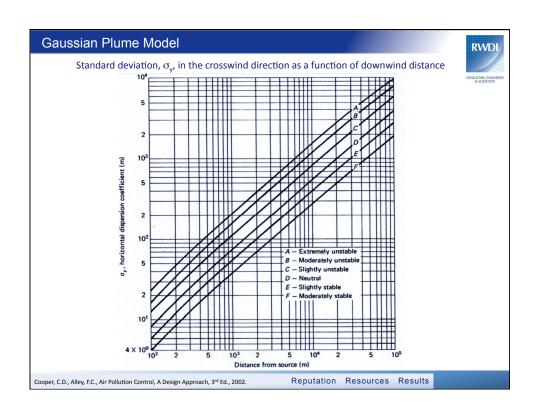
$$\sigma = e^{I + J \cdot \left[\ln \left(\frac{x}{1000} \right) \right] + K \cdot \left[\ln \left(\frac{x}{1000} \right) \right]^2}$$

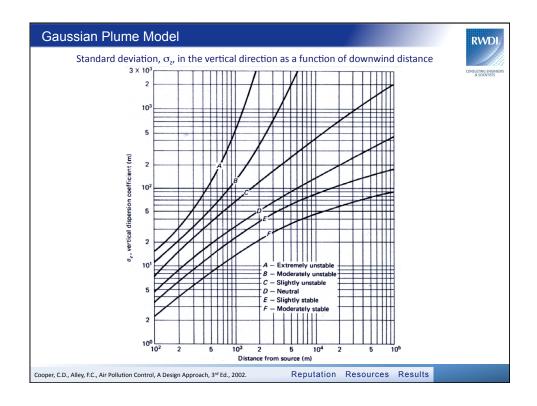
• Urban Conditions:

$$\sigma = \left[L \left(\frac{x}{1000} \right) \right] \left[1 + M \left(\frac{x}{1000} \right) \right]^{N}$$

Gaussian Plu	ussian Plume Model Rural Equation Coefficients					
	σ_{x}			σ_{y}		CONSULTING ENGINEE & SCIENTISTS
Stability	I	J	К	I	J	К
A	6.035	2.1097	0.2770	5.357	0.8828	-0.0076
В	4.694	1.0629	0.0136	5.058	0.9024	-0.0096
С	4.110	0.9201	-0.0020	4.651	0.9181	-0.0076
D	3.414	0.7371	-0.0316	4.230	0.9222	-0.0087
E	3.057	0.6794	-0.0450	3.922	0.9222	-0.0064
F	2.621	0.6564	-0.0540	3.533	0.9191	-0.0070
cMullan, R.W., JAPCA, Octob	er 1975		Rep	utation Resou	irces Results	

		Rural Ed	quation Coeff	icients		CONSULTING EF
_		$\sigma_{_{\! X}}$			Σ_{y}	
Stability	L	М	N	L	М	N
А	240	1.00	0.50	320	0.40	-0.50
В	240	1.00	0.50	320	0.40	-0.50
С	200	0.00	0.00	220	0.40	-0.50
D	140	0.30	-0.50	160	0.40	-0.50
E	80	1.50	-0.50	110	0.40	-0.50
F	80	1.50	-0.50	110	0.40	-0.50





Gaussian Plume Model



- Often we're interested in simply finding where the maximum concentration occurs.
- Under neutral to near neutral conditions, the GPM can be re-written to give the maximum ground-level concentration at any point along the x-axis.
- This is possible because:
 - -z = 0 and y = 0.
 - $-\,\sigma_{\text{\tiny V}}\!/\sigma_{\text{\tiny Z}}$ is nearly independent of the distance, x.

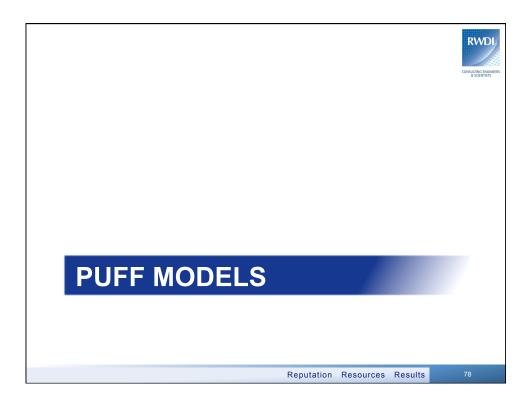
Gaussian Plume Model



• Thus the Gaussian equation can be written so that C is solely a function of σ_z :

$$\sigma_z = \frac{H}{(2)^{1/2}} = 0.707 \cdot H \qquad C_{\text{max,ref lec}} = \frac{0.1171 \cdot q}{U \cdot \sigma_y \cdot \sigma_z}$$

- H gives us σ_z .
- σ_z allows to calculate x, using the formulae presented earlier.
- x then allows us to find σ_y , also using the formulae presented earlier.



Puff Models



- Puff models (e.g., CALPUFF, SCIPUFF) are commonly used in other jurisdictions, but are not yet as popular in Ontario.
- Puff models differ from plume models primarily on the basis of time:
 - Plume models look at steady-state conditions only – there is no time dependence, the plume is "eternal".
 - Puff models can handle non-steady-state conditions, with an hour-by-hour dependence.

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Puff Models



- As a non-steady-state model, a puff model allows the user the flexibility of:
 - Continuous or variable source emission;
 - Variable meteorological conditions; and,
 - Three dimensional meteorology.
- This is balanced by a significant increase in set-up and processing time.
- Modelling a site with a puff model is often twice the cost of using a plume model.

Puff Models



- In situations where complex terrain or meteorological conditions are expected however, a puff model is usually far more accurate for predicting impacts.
- It would also be more reliable should the need arise for a forensic analysis, due to the ability to handle non-steady-state conditions.

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Puff Models

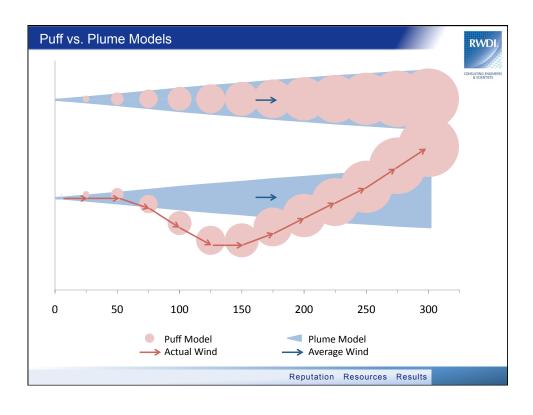


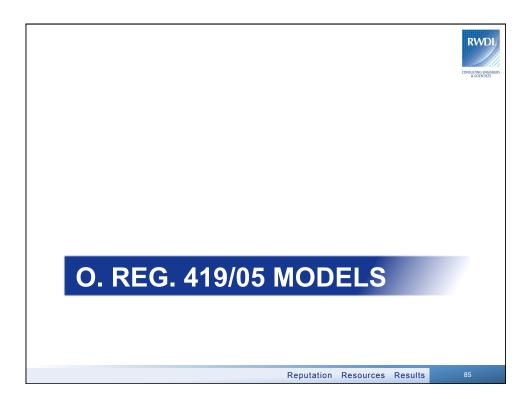
- At a very high level, a puff model uses the following approach:
 - At a given interval (from less than 1 minute, up to one hour), puffs are released from depending on their flow and emission rates.
 - The centre point of each puff (new and old) are calculated based on meteorology.
 - Plume heights are adjusted (plume rise, building downwash, terrain, etc.).
 - Dispersion of each plume is calculated

Puff Models



- Approach (continued):
 - Concentrations are adjusted for chemistry or deposition as required
 - Concentrations for all puffs impacting a receptor are summed together
 - Puffs that are very dispersed are removed from the model
 - And then we do it all again!





Models Approved under O. Reg. 419/05



- There are currently four dispersion models approved under O. Reg. 419/05:
 - AERMOD
 - ASHRAE
 - SCREEN3
 - Models in the Appendix to O. Reg. 346
- Each of these will be discussed today.

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Models Approved under O. Reg. 419/05



- There are also four "alternative" dispersion models identified in MOE Guideline A11 (Air Dispersion Modelling Guideline for Ontario):
 - CalPUFF
 - Cal3QHCR
 - SDM Shoreline Dispersion Model
 - Physical Modelling (e.g., wind tunnel)

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AERMOD



- AERMOD is the most advanced of the models currently approved under O. Reg. 419/05.
- It is a steady-state model that is best suited to short-range (<50km) modelling applications for stationary sources.
- It is based on a minimum 1-hour average, but can provide longer averaging periods, including monthly or annual averages.

AERMOD



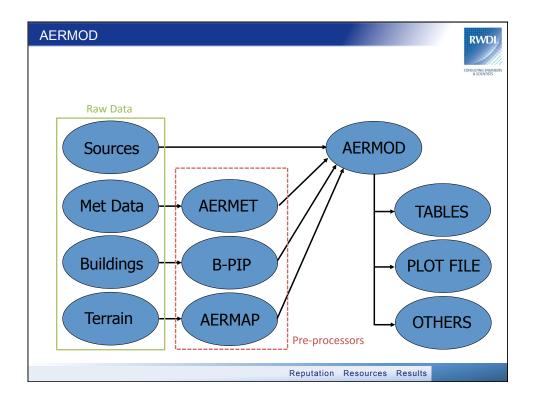
- AERMOD is developed and maintained by the U.S. EPA, and is available through "SCRAM", the Support Center for Regulatory Atmospheric Modeling
- Several Graphical User Interface (GUI) applications exist to help AERMOD users.
- These GUI applications are helpful tools, but should not replace an understanding of the model itself.

Reputation Resources Results

AERMOD



- AERMOD requires up to four different sets of inputs, depending on the application:
 - Source Information (required)
 - Meteorological Information (required)
 - Building Information (may be required)
 - Terrain Information (may be required)
- With the exception of the source data, preprocessing of this data is required.



AERMOD

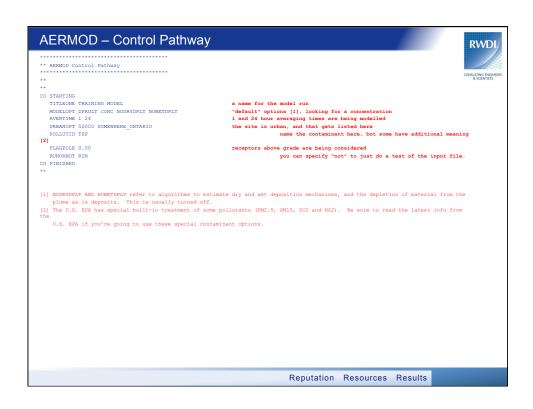


- Once processed, this data is incorporated into an AERMOD input file, set up in a structured manner with 5 "pathways":
 - Control Options (CO)
 - Source Information (SO)
 - Receptor Information (RE)
 - Meteorological Information (ME)
 - Output Options (OU)
- · We'll look at each pathway now.

AERMOD - Control Pathway

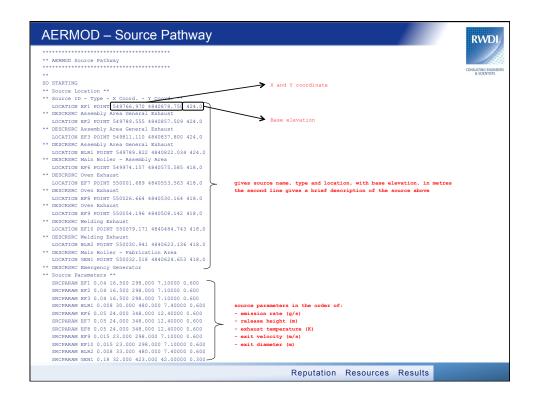


- The control pathway specifies overarching model settings that affect how the run proceeds.
- Simple things such as project names and the contaminant of interest are specified here as well.
- Averaging times, desired units, and the calling of subroutines is done here as well.





- Basic source information is entered into an AERMOD file in two areas.
- The first provides spatial data (x, y, z)
- The second provides the source parameters such as emission rate, height, exit diameter, etc.
- For area or volume sources, there will be alternative source parameters, such as initial plume height, etc.





- AERMOD also requires information on buildings, if present.
- Generally, buildings influence a stack if they are less than 5 times the height of the building from the source in question.
- Each level of the building must be identified, marked out by the footprint of each "tier".
- A good site plan is <u>critical</u>.

Reputation Resources Results

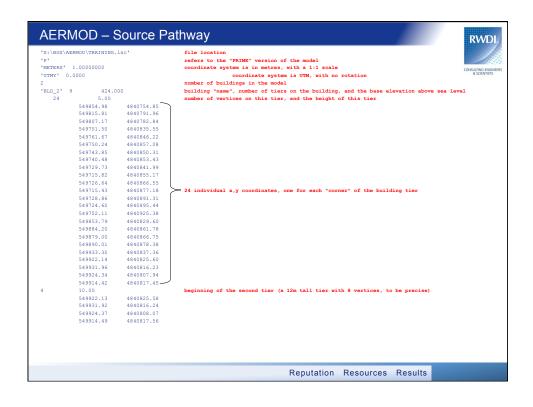
AERMOD - Source Pathway

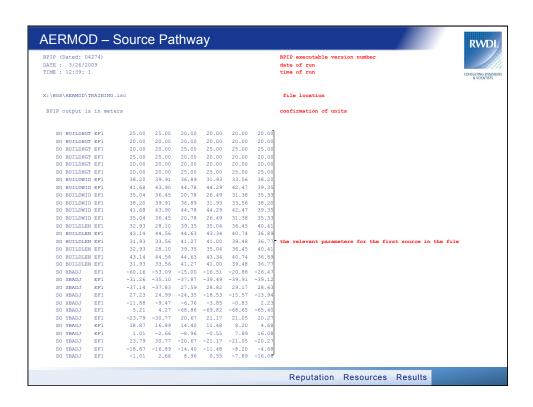


- Building information is entered into another pre-processor called B-PIP.
- B-PIP takes the building height and footprint information, along with the point source locations, and determines the downwash effects of the buildings, for 36 wind directions (in 10° increments).
- It produces a data set that is imported directly into AERMOD.



- It calculates the following:
 - BUILDHGT: height of the most dominant building upwind or downwind of stack.
 - BUILDWID: width of the most dominant building upwind or downwind of stack.
 - BUILDLEN: projected length of the building along flow
 - XBADJ: along-flow distance from stack to the center of upwind face of the projected building
 - YBADJ: across-flow distance from stack to the center of upwind face of the projected building







- The source pathway also allows the user to enter information on:
 - Temporal variations in source emissions;
 - Data pertaining to wet or dry depletion; and,
 - Source groupings (allows the model to produce results for specific sources or subgroups of sources).

AERMOD - Receptor Pathway



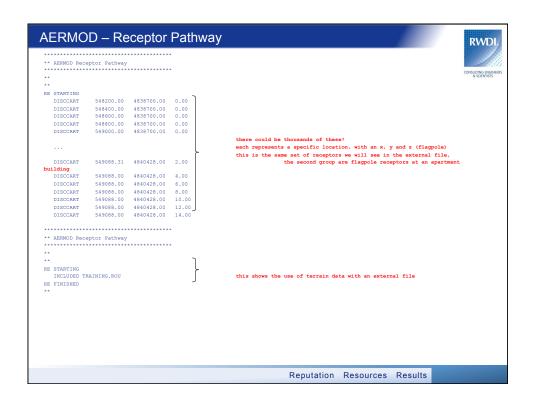
- Receptors must be entered for each location of interest, with a specific X, Y and Z (base elevation) coordinate.
- The base elevation refers to the elevation of the ground at that location above sea level.
- In addition, a "flagpole" height allows you to look at a location at a point somewhere above that base elevation (e.g. a balcony).

Reputation Resources Results

AERMOD - Receptor Pathway



- When not using terrain data, the receptors are listed in the AERMOD input file itself.
- When using terrain data (changing base elevations), an external file is created and called.
- The next slide shows how both options appear in the ME Pathway.



AERMOD - Receptor Pathway

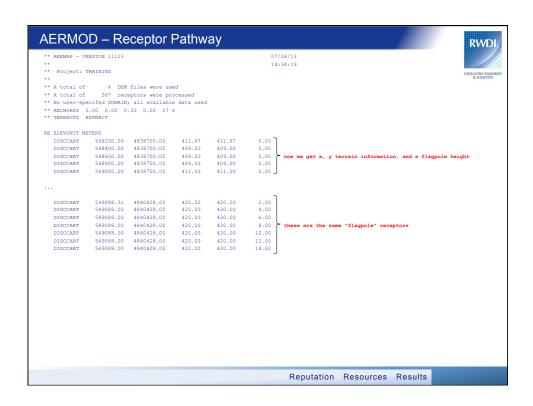


- Terrain data is sometimes required if the site is located in very hilly terrain (i.e., Niagara Escarpment)
- This data is normally obtained from Natural Resources Canada (NRCan) in "DEM" format, or the MOE's Ontario Digital Elevation Model Data.
 - www.geobase.ca
 - http://www.ene.gov.on.ca/environment/en/ resources/STDPROD_078093.html

AERMOD - Receptor Pathway



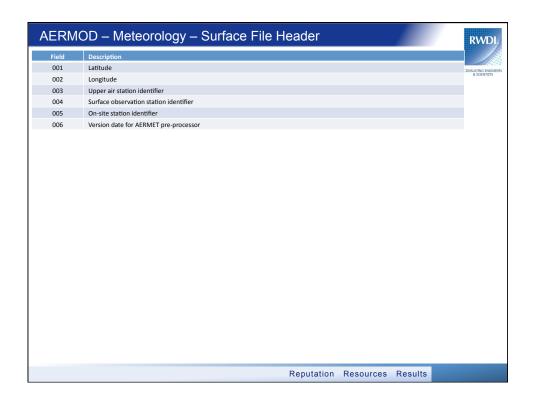
- Terrain data is normally used to modify the base elevations of receptors, but you can also allow the pre-processor to alter source and building base elevations as well (this is usually a bad idea, however).
- In the end, you end up getting an external file that looks something like this:



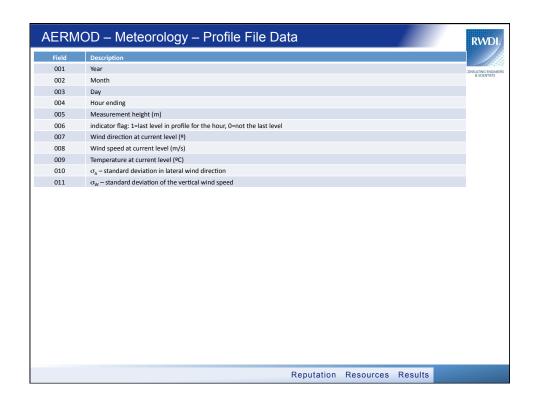
AERMOD - Meteorology Pathway



- AERMOD requires two external meteorological data files, known as the:
 - Profile File
 - Surface File
- These contain all the data required to model the emissions from the site in question.
- The formats for these text-based files are provided on the following slides.



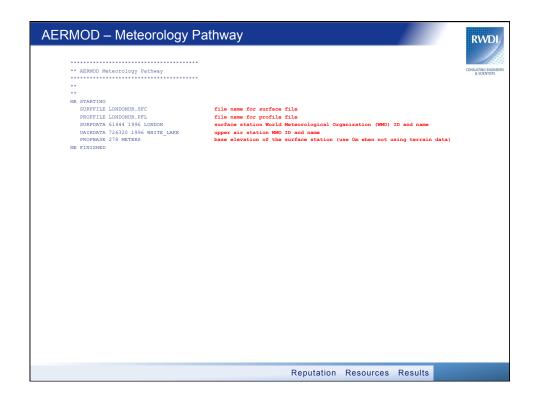
Field	Description	
001	Year	CONSULTI
002	Month	8 50
003	Day	
004	Julian Day	
005	Hour ending	
006	Sensible heat flux (W/m²)	
007	Surface friction velocity (m/s)	
800	Convective velocity scale (m/s)	
009	Vertical potential temperature gradient above planetary boundary layer	
010	Height of convectively-driven mixing height (planetary boundary layer) (m)	
011	Height of mechanically-driven mixing height (surface boundary layer) (m)	
012	Monin-Obukhov length (m)	
013	Surface roughness length (m)	
014	Bowen Ratio	
015	Albedo	
016	Wind speed (m/s)	
017	Wind direction (º)	
018	Reference height for wind speed and wind direction (m)	
019	Temperature (K)	
020	Reference height for temperature (m)	
021	Precipitation type code (0=none, 11=liquid, 22=frozen, 99=missing)	
022	Precipitation amount (mm/hr)	
023	Relative humidity (percent)	
024	Station pressure (mb)	
025	Cloud cover (tenths)	
026	Wind speed adjustment and data source flag	



AERMOD - Meteorology Pathway



- The Meteorology Pathway specifies these two files, as well as information regarding the meteorological stations from which this data was gathered.
- This pathway is pretty simple, although in some cases you can invoke other options, such as looking at specific periods within a meteorological data record.
- A sample is on the next slide.



AERMOD - Meteorology Pathway



- In order to generate the surface and profile files, we must run a pre-processor known as AERMET (or use pre-processed data).
- This data comes in a number of different file formats, but must contain:
 - Surface Data (e.g., from an airport)
 - Upper Air Data (e.g., weather balloons)
- AERMET adjusts the data to account for local conditions (land use, vegetation, etc.)

Reputation Resources Results

AERMOD – Meteorology Pathway

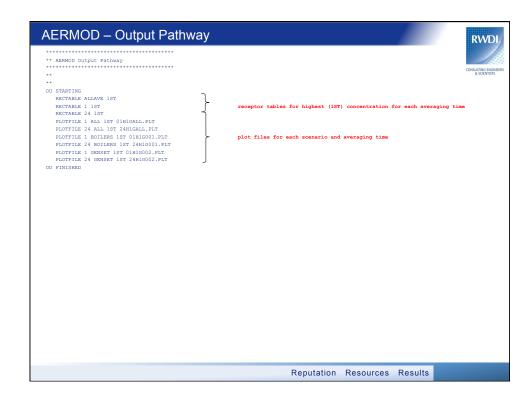


- The MOE has made this process a little easier by pre-processing the data for several regions in Ontario.
- These constitute a "screening" data set, and can be used in support of Certificates of Approval or the STAC initiative.
 - http://www.ene.gov.on.ca/environment/en/ resources/STDPROD_078072.html

AERMOD - Output Pathway



- The output pathway specifies what files will actually be generated by the model.
- Most common are "receptor tables" which give the maximum value at all receptors, and "plot files" that allow us to generate contours.



AERMOD



- Overall, an AERMOD input file is akin to computer coding, with specific structure and syntax.
- It can be done in a text editor, but there are a few key items to remember:
 - Letters and numbers only.
 - If a line has a ** in the first two columns, the model ignores it – it's where you add comments.
 - D not use "tabs". Spaces only.

Reputation Resources Results

SCREEN3



- Published in 1995.
- Screening level version of the ISC3ST model, the ancestor of AERMOD.
- Based on fixed set of meteorological data.
- · Gives 1-hour concentrations.
- Also includes cavity calculations that give a rough estimate of concentrations in the rear recirculation cavity of the building.

SCREEN3



- Models point sources, area sources, volume sources and flares.
- · Can model single sources only!
- Able to predict the plume centre-line height at any distance downwind, which is very useful for looking at elevated receptors.

Reputation Resources Results

SCREEN3



- SCREEN3 can also model the special dispersion characteristics of flares.
- Because flares produce a great deal of heat, dispersion near the flare tip is dominated by this additional energy.
- Knowing the heating value of the gas being flared allows the model to adjust the stack parameters to account for this influence.

SCREEN3



- The model also performs building downwash calculations for both the "near wake" and far "wake regions".
 - "Near wake" extends from 3L_b to 10L_b.
 - "Far wake" for distances greater than 10L_b.
 - L_b is the lesser of the building height, h_b, and the maximum projected width.
 - The maximum projected width is calculated from the input minimum and maximum horizontal dimensions as (L² + W²)^{0.5}.

Reputation Resources Results

SCREEN3

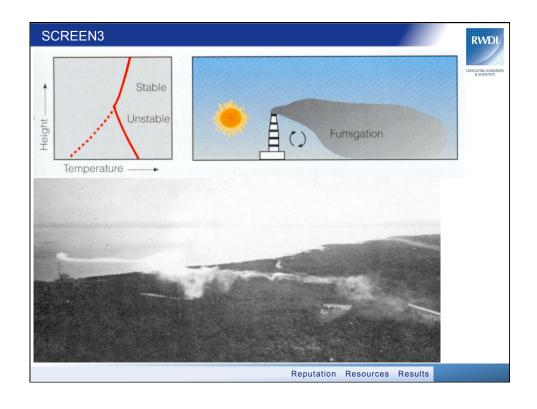


- In addition, SCREEN3 also performs inversion break-up fumigation calculations.
 - The distance to maximum fumigation is based on an estimate of the time required for the mixing layer to develop from the top of the stack to the top of the plume.
 - The mixing layer is the atmospheric layer between the Earth's surface and the bottom of the inversion aloft.

SCREEN3



- SCREEN3 also performs shoreline fumigation calculations for rural sources within 3000m of a large body of water.
 - The maximum concentration is assumed to occur where the top of the stable plume intersects the top of the well-mixed thermal internal boundary layer (TIBL).
 - The TIBL is an internal boundary layer caused by advection of air across a discontinuity in surface temperature.





- Three main models were written into the old Ontario Regulation 346:
 - Scorer Barrett Equations (self-contamination)
 - Maximum Ground Level Concentration Model
 - Concentration at Points Model
- These models are still the regulatory models until the year 2020 for some facilities, even if they won't run on modern computers.

Reputation Resources Results

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Models in the Appendix to O. Reg. 346



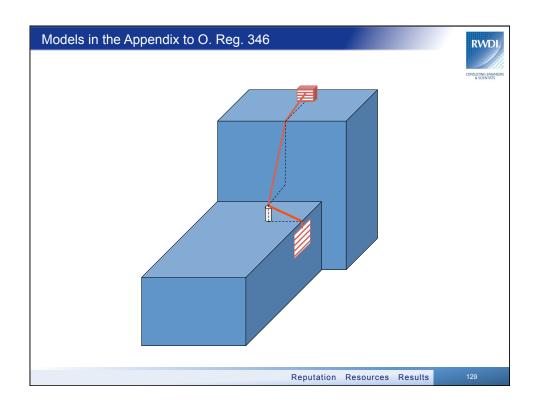
 The Scorer-Barrett equation is the calculation for self-contamination:

$$C = \frac{0.6 \times 10^6 Q}{L^2}$$

- · Where:
 - L = 1.57 times the stretched string distance in metres if the receptor is lower than the emission point, otherwise,
 - L = the stretched string distance if the receptor is higher than the emission point.
 - Q = emission rate in grams per second

Reputation Resources Results

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- The MOE provides a computer modelling package for off-site concentrations:
 - Maximum Ground Level Concentration Model
 - MAXGLC.exe
 - Concentration at Points Model
 - CAP.exe
- There are other applications in this package, but are not generally used.
- You will also likely need a DOS emulator to be able to run these models.



- Both models require site, property line and source information, stored in an "STK" file, generated by the Source Database Manager (SDBMGR.exe)
- The CAP model also requires receptor information, stored in a "PTI" file, generated by the Point Database Manager (PDBMGR.exe).

Reputation Resources Results

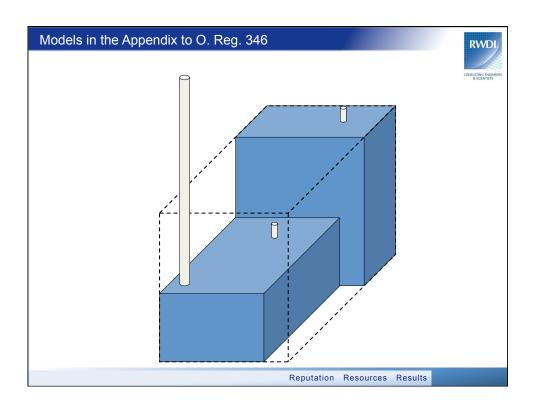
Models in the Appendix to O. Reg. 346



- When defining sources, point sources are:
 - Stacks with heights greater than twice the building height above grade; or,
 - Stacks with heights greater than 20m above the roof for buildings with a roof height greater than 20m above grade.
- Virtual sources are anything below that, unless a stack is greater than 100m away from any buildings.



- The virtual source turns a building and it's (short) stacks into a large box.
- Multiple short sources with the same contaminant can be modelled as a single virtual source.
- For very large buildings, the MOE has accepted point sources based on the local roof, if taller portions of the building are located far away.





- Receptors of interest are incorporated into the model using the Point Database Manager.
- This tool requires that receptors be identified as either being "open" or "closed":
 - Open: finds maximum value anywhere between the ground and the height enetered
 - Closed: finds value at indicated height only

Reputation Resources Results

Models in the Appendix to O. Reg. 346



- These programs are very old, so be very careful when you type:
 - The arrow keys don't work.
 - Delete doesn't work.
 - If you type it wrong and hit enter blindly, you may end up starting over!
 - File names longer than 8 characters don't work!
 - Letters and numbers only!